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## THE DRAG-BASED MODEL IN A COMPLEX NUMERICAL ENVIRONMENT

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# The Drag-based Model

- The DBM hypothesis – at large heliocentric distances:
  - observational facts: ICME dynamics is solely governed by interaction with solar wind (ambient)
  - the Lorentz force ceases in upper corona, only drag is dominant; net acceleration is

$$a = a_L + a_g + a_d$$

- collisionless environment – low viscosity and low resistivity:
  - dissipative processes are negligible
  - momentum and energy are transferred by magnetosonic waves
- equation of motion is in a quadratic form (Cargill, 2004):

$$R''(t) = -\gamma(R)[R'(t) - w(R)][R'(t) + w(R)]$$

- parameter  $\gamma$ :

$$\gamma(R) \propto c_d \frac{A \rho_{sw}}{M} = \gamma_\infty \frac{w_\infty}{w(R)}$$

$$\gamma_\infty := \lim_{R \rightarrow \infty} \gamma(R) = \Gamma \times 10^{-7} \text{ km}^{-1}$$

- solar wind speed (unperturbed  $w_0$  + perturbed  $w_p$ ):

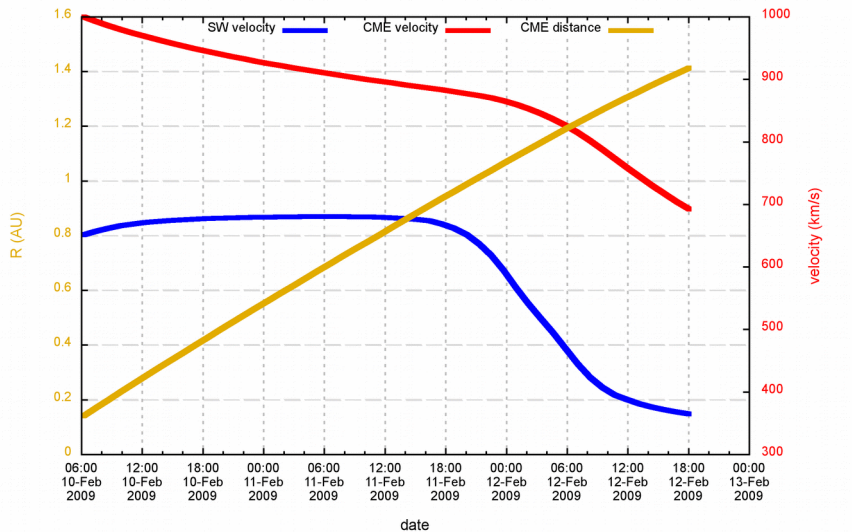
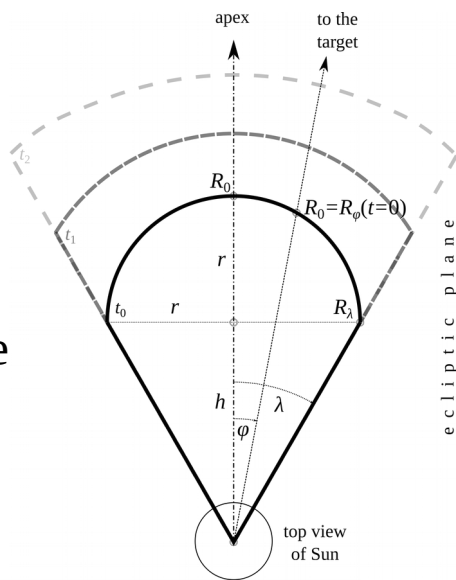
$$w(R) = \begin{cases} w_0(R) + w_p(R), & R_1 < R < R_2 \\ w_0(R), & \text{otherwise} \end{cases} \quad w_0(R) = w_\infty \left( 1 + \frac{k_4/k_2}{R^2} + \frac{k_6/k_2}{R^4} \right)^{-1} \quad w_\infty = \lim_{R \rightarrow \infty} w_0(R)$$

- The DBM: a „tool“ for prediction of ICMEs propagation in the heliosphere
  - primary task for space-weather forecasting

# Example of DBM + ENLIL model

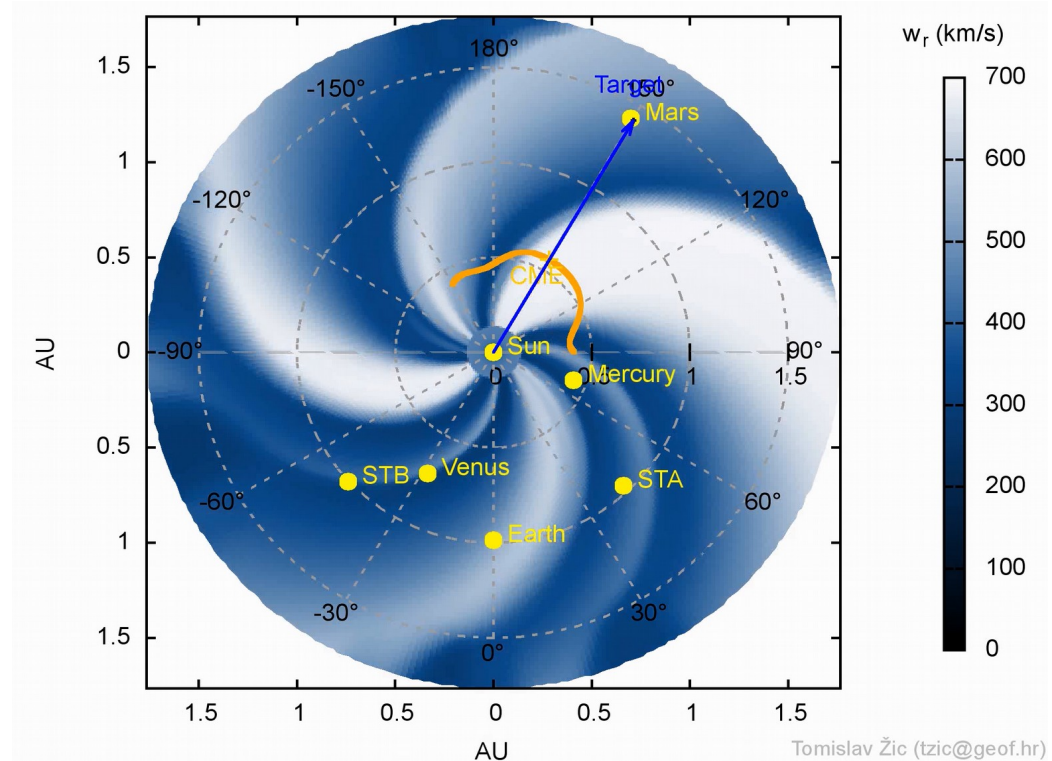
(<http://oh.geof.unizg.hr/~tomislav/DBM-ENLIL/>)

- solar-wind speed and  $w(R)$  and parameter  $\gamma(R)$  are radially dependent
- CME leading-edge segments propagate independently
- initial cone shape flattens



Propagation of '+ CME' point in geometry plot

$w(R)$ ,  $\gamma(R)$  → CME-edge flattening:  $\Gamma = 0.2$ ,  $R_0 = 31 r_s$ ,  $v_0 = 1000$  km/s,  
 $\lambda = 60^\circ$ ,  $\varphi = 150^\circ$ , target: Mars



**Cross-section of CME propagation in ecliptic plane**  
 The CME take-off time: February the 10th, 2009 at 06:13 UT

# Automatic Fitting (LSF method)

- INPUT: observed ICME dataset:  $\{(R_0, v_0), \dots, (R_N, v_N)\}$
- OUTPUT: DBM parameters  $(\Gamma, w_\infty, R_0, v_0)$
- The least-square fitting (LSF):
  - successive variation of DBM parameters  $\rightarrow$  minimal deviation between observed  $v_i$  and DBM-calculated speeds  $v(R_i)$ :

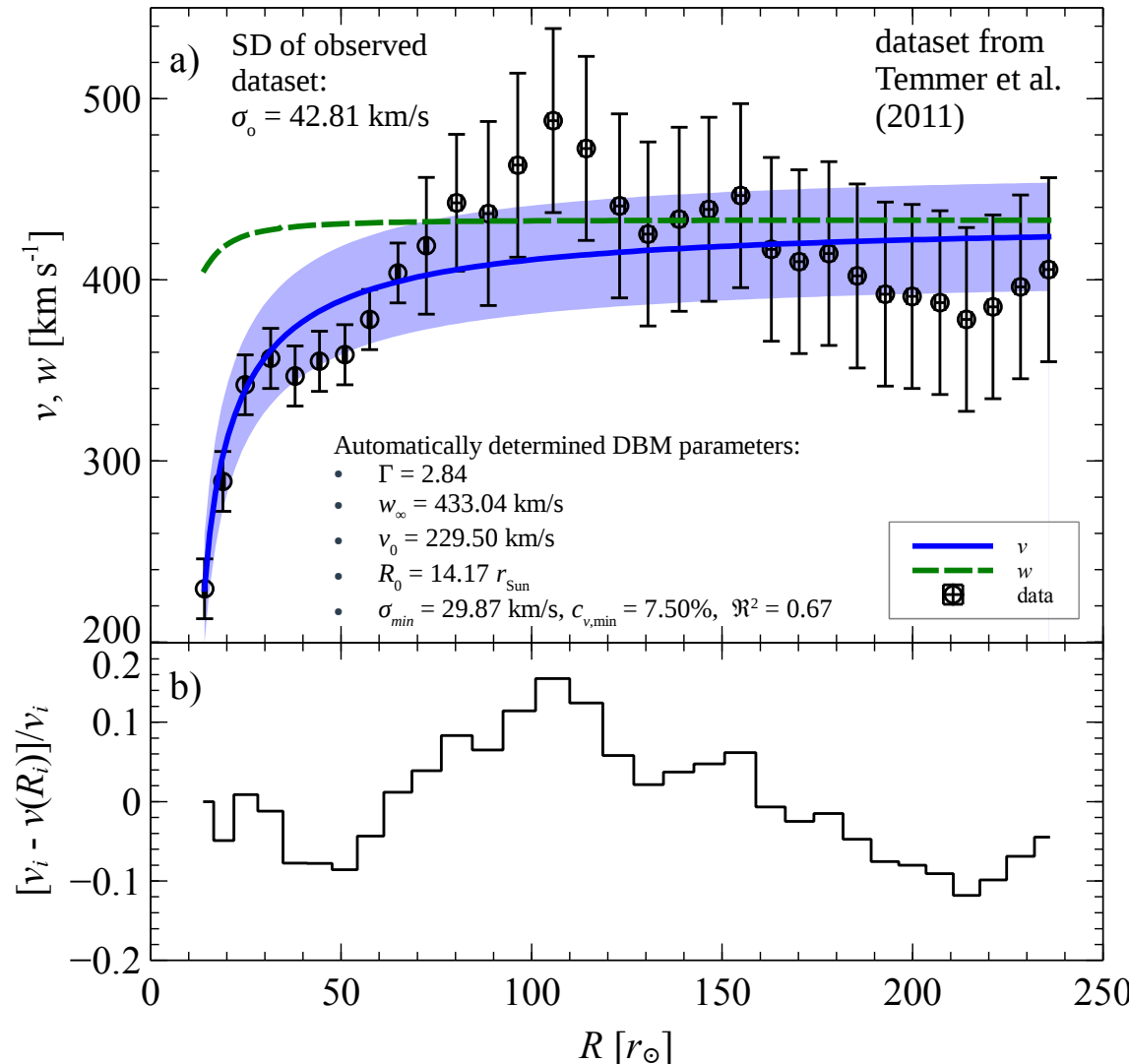
$$\sigma(\Gamma, w_\infty, R_0, v_0) = \sqrt{\frac{1}{(N+1)} \sum_{i=0}^N [v_i - v(R_i)]^2}$$

$\rightarrow \sigma_{\min} \rightarrow$

$\rightarrow$  the best  $(\Gamma, w_\infty, R_0, v_0)$

- for real-time space-weather forecasting (successive fitting as ICME propagates)

The fitted standard deviation  $\sigma_{\min}$  is smaller than the observed  $\sigma_0$ !



# Conclusion

- The drag-based model:
  - could be integrated to other advanced numerical codes as ENLIL and EUHFORIA
  - gives an availability for employment in practical and fast online CME prediction tools
- Drawbacks:
  - the magnetic field/Lorentz force is not included in the DBM
  - CME-CME interaction is problematic for calculation
- The LSF method:
  - opens an opportunity for implementation in real-time space-weather forecasting tools and alerting systems for CME impacts on any heliospheric “target” of interest
  - the novel approach: real-time data-driven DBM-parameter optimization improves the accuracy of CME kinematics in the heliosphere
- The current and development DBM versions are available at web-site:

<http://www.geof.unizg.hr/~tzic/dbm.html>

## Acknowledgments

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