

Reflection of Cosmic Rays at Oblique MHD Shocks

Bojan Vršnak (Faculty of Geodesy, University of Zagreb, Croatia)

Anamarija Kirin (University of Applied Sciences, Karlovac, Croatia)

Mateja Dumbović (Institute of Physics, University of Graz, Austria)

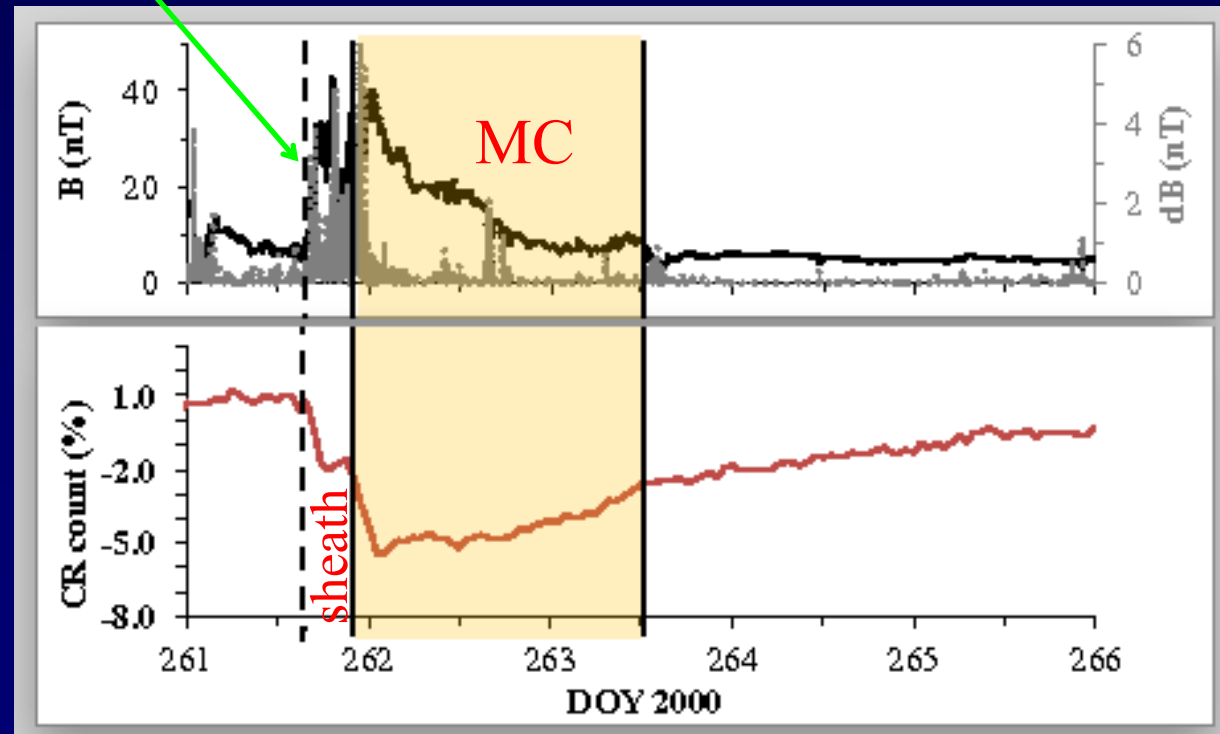
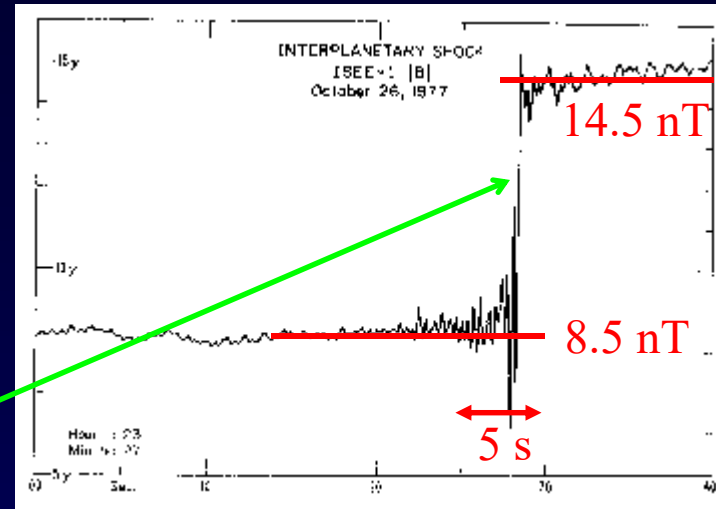
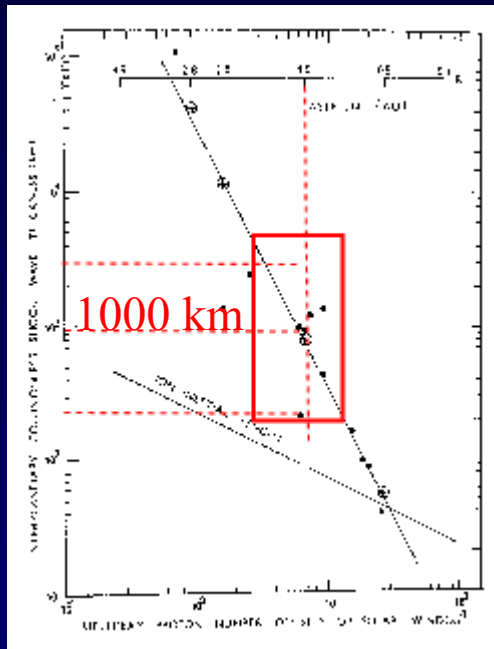
Bernd Heber (Christian-Albrechts-Universität, Kiel, Germany)



HRZZ-IP-11-2013 6212-SOLSTEL
“Solar and Stellar Variability”

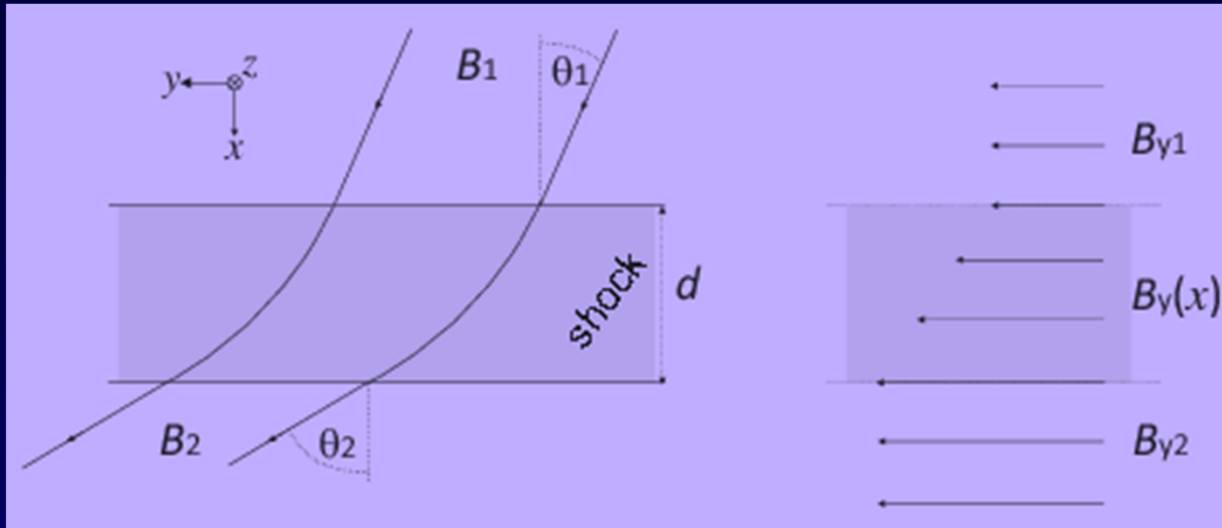


Introduction



The Model

oblique 2D MHD shock
(z -invariant, $B_z=0$)



Pinter 1980:
 $d \sim 1000$ km
i.e.
 $d \ll r_L$
 $\Delta t(d) \ll t_{\text{cycl}}$

flux conservation: $B_{x1} = B_{x2} \Rightarrow B_x(x) = \text{const.}$, i.e., $\partial B_x / \partial x = 0$;

$\text{div} B = 0 \Rightarrow \partial B_y / \partial y = 0$, i.e., $B_y(y) = \text{const.}$

approximation:

$$B_y(x) = B_{y1} + kx \quad (k = \Delta B_y / d, \quad \Delta B_y = B_{y2} - B_{y1})$$

Particle motion

$$d \ll r_L, \quad \Delta t(d) \ll t_{\text{cycl}}$$

~~=> guiding centre approx.,
magnetic moment conservation~~

incoming particle: v_x, v_y, v_z

Lorentz force: $m\mathbf{a} = q\mathbf{v} \times \mathbf{B}$; $m = \gamma m_0$

$$a_x = -q/m v_z B_y$$

$$a_y = q/m v_z B_x$$

$$a_z = q/m (v_x B_y - v_y B_x)$$

$$B_x = \text{const.}$$

$$B_y = B_{y1} + kx$$

“Components” of Particle Motion

$$a_x = -q/m [v_z B_{y1} + v_z \Delta B_y(x)]$$

$$a_y = q/m v_z B_x$$

$$a_z = q/m [v_x B_{y1} + v_x \Delta B_y(x) - v_y B_x]$$

$$\Delta B_y(x) = \Delta B_y x/d$$

$$\Delta B_y = B_{y2} - B_{y1}$$

“components”:

- cyclotron rotation related to B_1 (written in a coordinate system inclined by θ_1 from the B_1 direction)
- ΔB_y effect: decelerates/accelerates particle in x-direction, accelerates/decelerates particle in z-direction ($v_x^2 + v_z^2 = \text{const.}$)

ΔB_y effect = shock effect

$$a_x \equiv \dot{v}_x = -q/m v_z \Delta B_y(x)$$

(magnetic-mirror “equivalent”)

$$a_z \equiv \dot{v}_z = q/m v_x \Delta B_y(x)$$

the system can be solved numerically for a given function $\Delta B_y(x)$

or analytically in an approximative form:

a=const. approximation:

$$1. a_x(x) \rightarrow \{a_x\} = -q/m \{v_z\} \{\Delta B_y\}$$

$$2. a_z(x) \rightarrow \{a_z\} = q/m \{v_x\} \{\Delta B_y\}$$

$$\begin{aligned} \{\Delta B_y\} &= (B_{y2} - B_{y1})/2 = \\ &= (B_{y2}/B_{y1} - 1) B_{y1}/2 = \\ &= \mathcal{B} B_{y1}/2 \end{aligned}$$

Reflection ($v_{x2} = 0$)

$$x(t) = v_{x1} t + \{a_x\} t^2/2 \quad , \quad v_x(t) = v_{x1} - \{a_x\} t$$

reflection if: $v_x = 0$ at $x = x_0 < d$

i.e., if the stopping distance $x_0 = v_{x1}^2 / 2\{a_x\}$ is $x_0 < d$

all particles with $v_{x1} < (2\{a_x\}d)^{1/2}$ are reflected

=> for a given $\{a_x\} = f(v_{z1})$,

find critical v_{x1} for which $x_0 = d$

$$\mathcal{B} = B_{y2} / B_{y1} - 1$$

$$\{v_x\} = v_{x1}/2$$

$$\Rightarrow \{a_z\} = q/m \{v_x\} \{\Delta B_y\} = q/m v_{x1} \mathcal{B} B_{y1} d/4$$

$$v_{z2} = v_{z1} + \{a_z\} t_d = v_{z1} + \{a_z\} d / \{v_x\} = v_{z1} + 2\{a_z\} d / v_{x1}$$

$$\{v_z\} = (v_{z1} + v_{z2}) / 2 = \dots = v_{z1} + q/m \mathcal{B} B_{y1} d/4$$

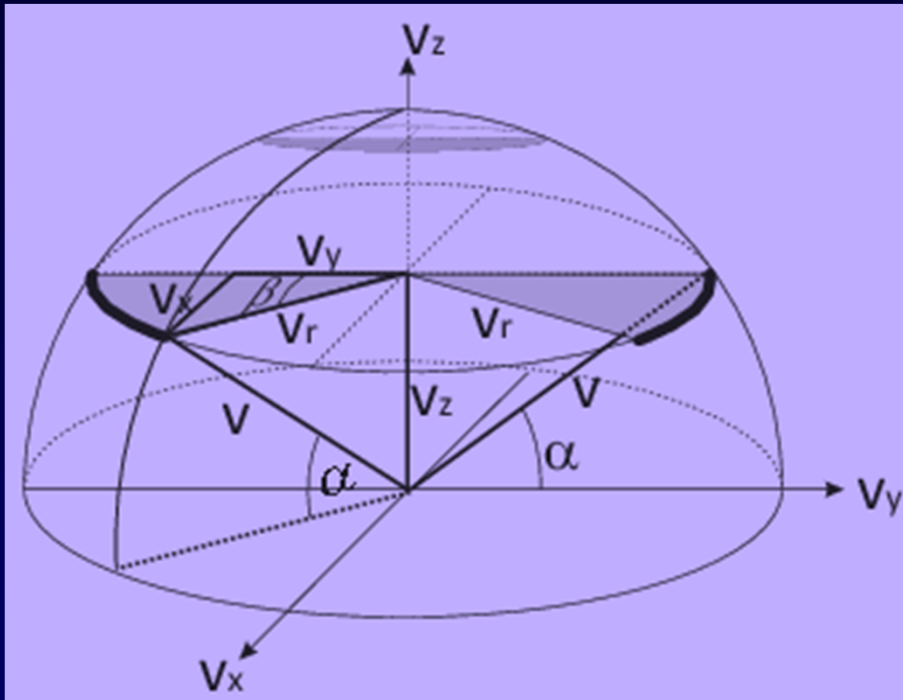
$$\{a_x\} = q/m \{v_z\} \{\Delta B_y\} = q/m (v_{z1} + q/m \mathcal{B} B_{y1} d/4) \mathcal{B} B_{y1} / 2$$

finally, we get the equation determining critical v_{x1} :

$$v_{x1}^2 = q/m (v_{z1} + \boxed{q/m \mathcal{B} B_{y1} d/4}) \mathcal{B} B_{y1} d$$

$$= 4A (v_{z1} + A)$$

Integral over the Velocity Space



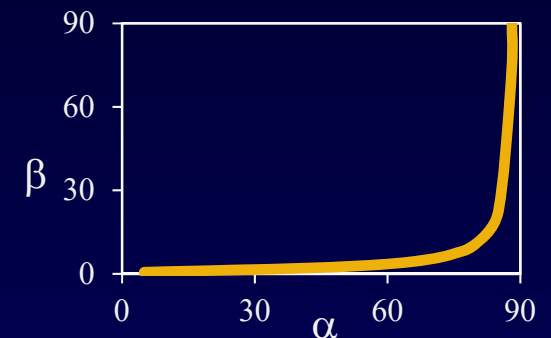
$$\sin \alpha = v_z/v$$

$$\cos \alpha = v_r/v$$

$$\sin \beta = v_x/v_r$$

$$= v_x/v \cos \alpha$$

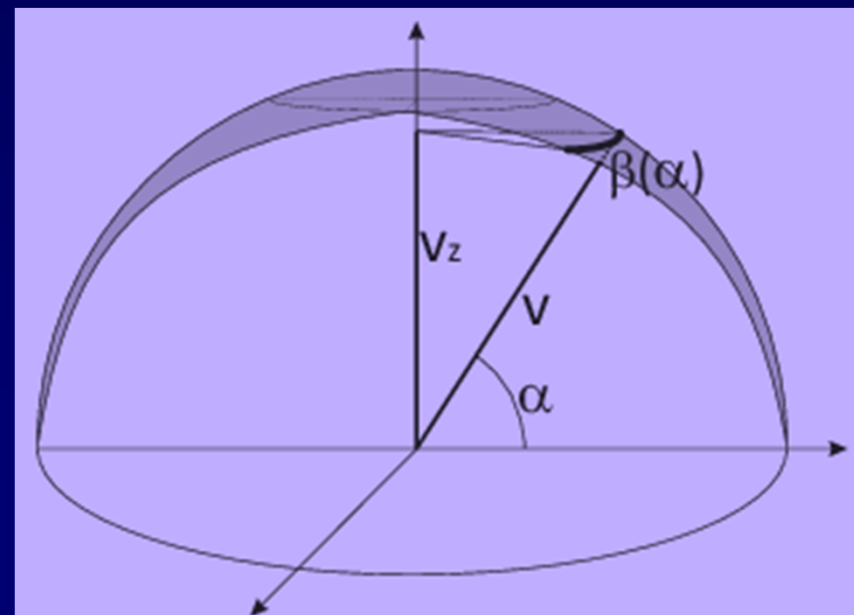
$$= (4A(\sin \alpha + A/v)/v)^{1/2} / \cos \alpha$$



$$\mathcal{A}_1 = \int_0^{\alpha_0} \int_0^{\beta(\alpha)} \cos \alpha \, d\alpha \, d\beta / \pi$$

$$\mathcal{A}_2 = \int_0^{2\pi} \int_{\alpha_0}^{\pi/2} \cos \alpha \, d\alpha \, d\beta / 2\pi$$

$$\mathcal{A} = \mathcal{A}_1 + \mathcal{A}_2$$



Integral over the Velocity Space

for a given v_{z1} , particles with $v_{x1}^2 < 4A(v_{z1} + A)$ are reflected [$A = q/m \mathcal{B} B_{y1} d/4$]

limits:

1. $v_{x1} > 0$

2. $v_{z1} > -A$

3. for a given v_{z1} , the largest v_{x1} (i.e., when $v_{y1}=0$) is defined by $v_{x1}^2 + v_{z1}^2 = v^2$

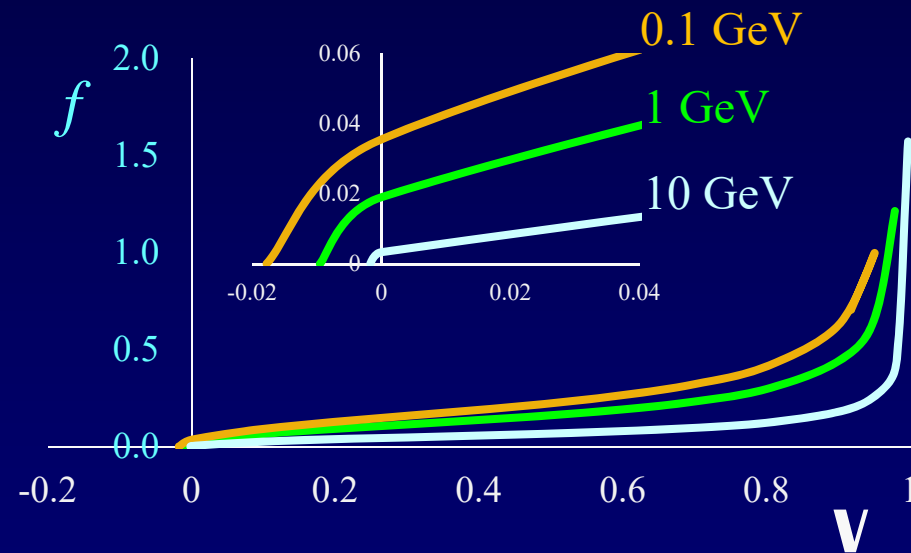
$$v^2 - v_{zc}^2 = 4A(v_{zc} + A) \quad (\text{for } v_{z1} > v_{zc} \text{ all reflected})$$

$$v_{zc} = -2Av_{zc} + [4A^2v_{zc}^2 - (4A^2 - v^2)]^{1/2}$$

Integral over the Velocity Space

$$\mathcal{A}_1 = 1/\pi \int_{\mathbf{V}_0}^{\mathbf{V}_C} \text{asin} \left[\left(\frac{(\mathbf{V}v/A + 1)}{(1 - \mathbf{V}^2)} \right)^{1/2} 2A/v \right] d\mathbf{V}$$

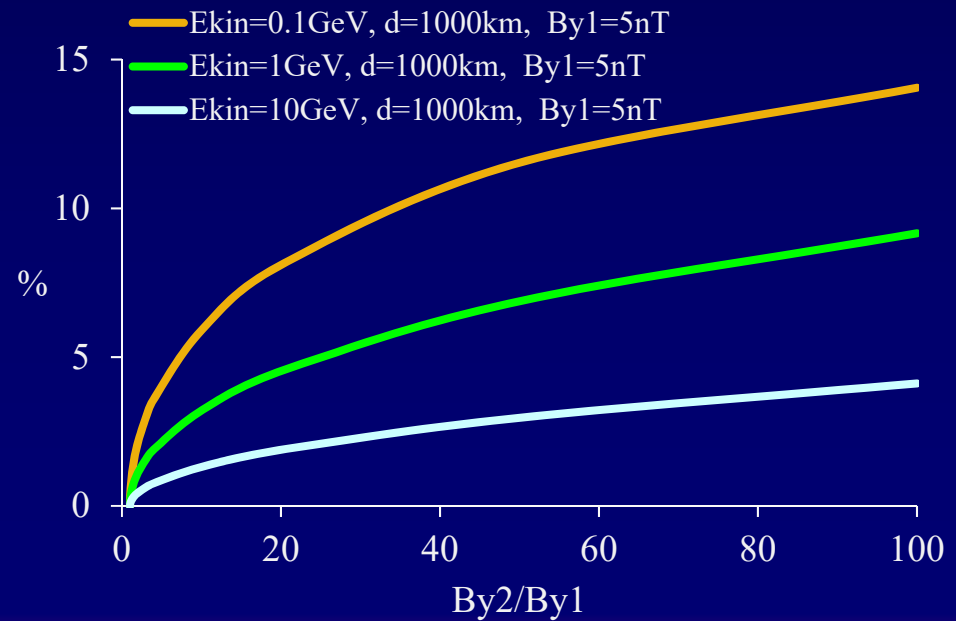
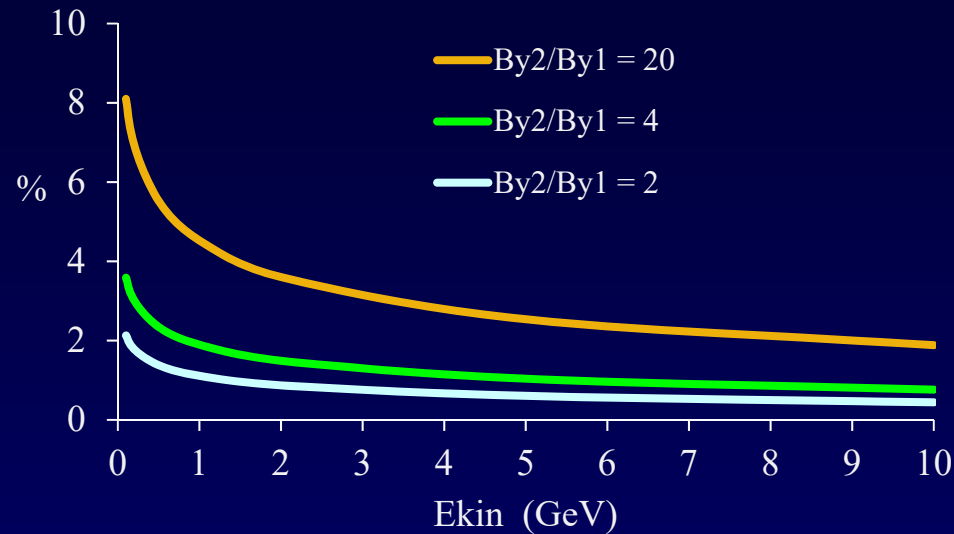
$$(\mathbf{V} = v_z/v \ ; \ \mathbf{V}_0 = -A/v \ ; \ \mathbf{V}_C = v_{zC}/v)$$



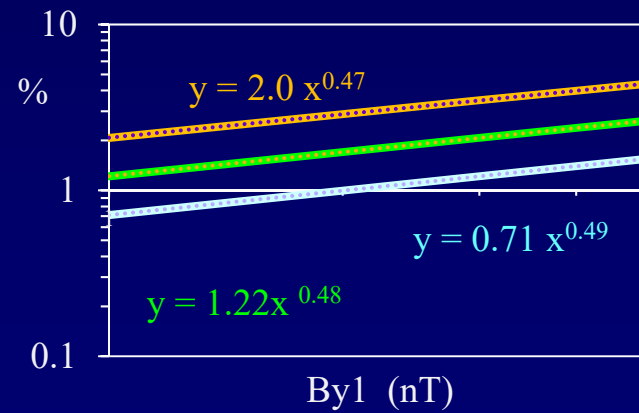
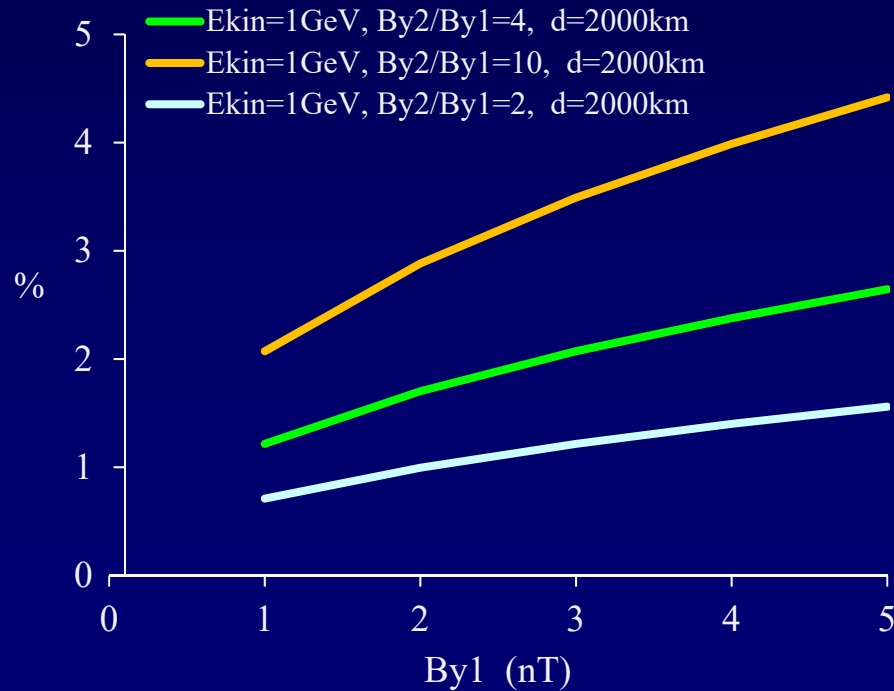
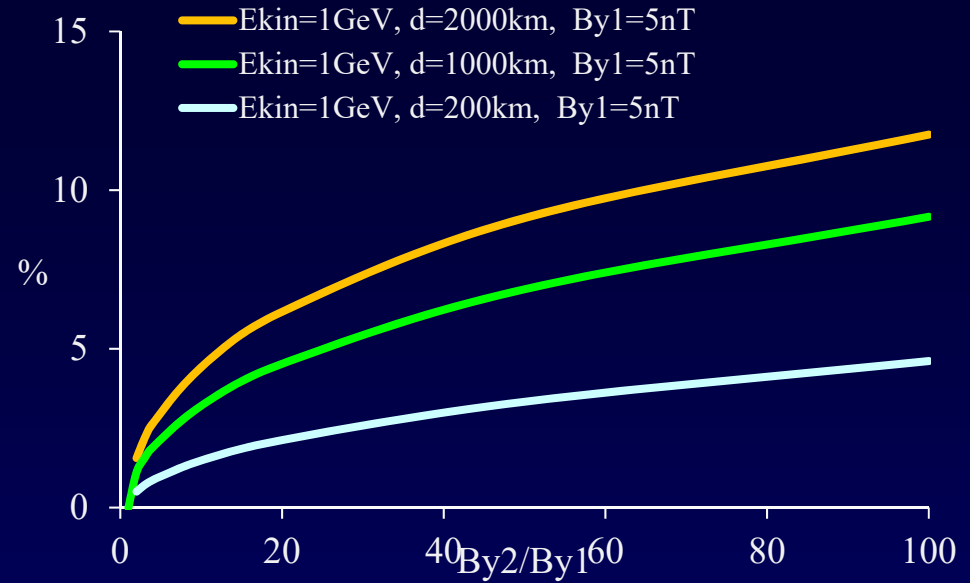
$$\mathcal{A}_2 = (1 - v_{zC}/v) / 2$$

$$\mathcal{A} = \mathcal{A}_1 + \mathcal{A}_2 \quad (\mathcal{A}_2 \ll \mathcal{A}_1)$$

Results: Energy Dependence



Results for $E_{kin} = 1 \text{ GeV}$



$$\mathcal{A} \sim B_{y1}^{1/2} ; \mathcal{A} \sim d^{1/2}$$

**Thank you for
your attention !**